# Sufficient conditions that the shift-invariant system is a frame for $L^{2}\left(\mathbb{R}^{n}\right)^{1}$ 

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Abstract. The main contribution of this paper is twofold. First, some new su $\pm$ cient conditions, under which the shift-invariant system is a frame for $L^{2}\left(\mathbb{R}^{n}\right)$, were established. Second, those su $\pm$ cient conditions are used to obtain some new results about Gabor frames.

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## 1. Introduction

The theory of frames, or stable redundant non-orthogonal expansions in Hilbert spaces, introduced by Du $\pm n$ and Schae®er ([1]), plays an important role in wavelet theory ( $[2-3]$ ) as well as in Gabor analysis ( $[4-6])$ for functions in $L^{2}\left(\mathbb{R}^{n}\right)$. Traditionally, frames were used in signal processing because of ther resilience to additive, resilience to quantization and because they give greater ${ }^{\circ}$ exibility to capture important signal characteristic([7-8]). Today, frame theory has a myriad of applications in pure mathematics, applied mathematics and even wiresess communication ([9-10]).

In [11], by the study of shift-invariant subspaces of $L^{2}\left(\mathbb{R}^{n}\right)$, the author presented a general result to dharacterize tight frame generators for the shift-invariant subspaces. Some applications of this general result are then obtained, among which are the characterization of tight wavelet frames and tight Gabor frames.

In [12], some necessary and su $\pm$ cient conditions ensuring that the shift-invariant system is a frame for $L^{2}\left(\mathbb{R}^{n}\right)$ were established, and then some known results about wavelet frames and Gabor frames were obtained by applying these conditions.

[^0]In present paper, we will give some new su $\pm$ cient conditions under which the shiftinvariant system is a frame for $L^{2}\left(\mathbb{R}^{n}\right)$. As some applications, the results are used to obtain some new conclusions about Gabor frames.

This paper is organized as follows. Section 2 includes some notations, de- nitions and auxiliary results. In order to prove the main results, some lemmas are given in Section 3 . Section 4 is devoted to the discussion of su $\pm$ cient conditions for the shiftinvariant system to be a frame. Section 5 contains applications of main results to Gabor frames.

## 2. Preliminaries

Some notations, de nitions and auxiliary results are listed in this section.
Firstly, several de- nitions and a fact about the frames are given. Additional information on the subject can be found in [3-9].

Definition 2.1 Suppose that $H$ is a separable Hilbert space and a countable family $\left\{x_{\mathrm{i}} \mid i \in I\right\} \subset H$. If there exist constants $0<A \leq B<\infty$ such that $\forall x \in H$,

$$
\begin{equation*}
A\|x\|^{2} \leq{ }_{\mathrm{i} \in 1}^{\mathrm{X}}\left|\left\langle x, x_{\mathrm{i}}\right\rangle\right|^{2} \leq B\|x\|^{2}, \tag{1}
\end{equation*}
$$

then $\left\{x_{\mathrm{i}} \mid i \in I\right\}$ is called a frame for $H$, where the numbers $A$ and $B$ are called the lower and upper frame bounds of the frame, respectively. A frame is a tight frame if $A$ and $B$ can be chosen so that $A=B$, and is a normalized tight frame if $A=B=1$.

Lemma $2.1\left\{x_{\mathrm{i}} \mid i \in I\right\}$ is a frame for $H$ if and only if (1) holds for all $x \in \mathcal{M}$, where $\mathcal{M}$ is dense in $H$.

The translation operator
and the inverse Fourier transform is Z
where $\xi \cdot x$ denotes thestandard inner product in $\mathbb{R}^{\mathrm{n}}$. We also use the standard notation $\|f\|$ for the norm of $f \in L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$, and $\langle f, g\rangle$ for the usual inner product of $f, g \in L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$.

Throughout the paper, $\mathbb{Z}$ is the set of all integers, the space $\mathbb{T}^{n}$ will be identi ${ }^{-}$ed with $[0,1]^{n}, G L_{n}(\mathbb{R})$ denotes the set of all non-singular $n \times n$ matrices with real entries and $\mathcal{D}$ is de ${ }^{-}$ned by

$$
\mathcal{D}=\left\{f \in L^{2}\left(\mathbb{R}^{\mathrm{n}}\right) \mid \hat{f} \in L^{\infty}\left(\mathbb{R}^{\mathrm{n}}\right) \text { and } \hat{f} \text { has compact support in } \mathbb{R}^{\mathrm{n}}\right\} .
$$

It is clear that $\mathcal{D}$ is a dense subspace of $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$. For $\forall C \in G L_{\mathrm{n}}(\mathbb{R})$, let $C^{1}:=\left(C^{\mathrm{t}}\right)^{-1}$, where $C^{\mathrm{t}}$ denotes the transpose of $C$.

## 3. Some Lemmas

In order to verify the results, we establish two lemmas in this section.
Lemma 3.1 Let $J$ be a countable indexing set, $\left\{f_{\mathrm{j}}(x) \mid j \in J\right\} \subset L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ and $C \in G L_{\mathrm{n}}(\mathbb{R})$. If ess $\sup _{\xi} \frac{1}{|\operatorname{det} C|}_{\mathrm{j} \in \mathrm{J}}\left|\widehat{f_{\mathrm{j}}}(\xi)\right|^{2}<\infty$, then for all $f \in \mathcal{D}$,

$$
\begin{align*}
& \mathrm{X} \times \mathrm{x} \underset{\mathrm{k} \in \mathbb{Z}^{n}}{ }\left|\left\langle f, T_{\mathrm{Ck}} f_{\mathrm{j}}\right\rangle\right|^{2}=\left.\underset{\mathbb{R}^{n}}{ }|\hat{f}(\xi)|^{2} \frac{1}{|\operatorname{de} C|}\right|_{\mathrm{j} \in \mathrm{~J}} \mathrm{X}|\hat{\mathrm{j}}(\xi)|^{2} d \xi+R(f), \tag{2}
\end{align*}
$$

where

$$
\begin{equation*}
R(f)=\mathrm{X}_{\mathrm{j} \in \mathrm{~J} m \neq 0}^{\mathrm{X}} \frac{1}{\operatorname{det} C \mid}_{\mathbb{R}^{n}}^{\mathrm{Z}} \hat{f(\xi) \overline{f_{\mathrm{j}}(\xi)} \hat{f_{\mathrm{j}}}\left(\xi+C^{\mathrm{l}} m\right) \overline{\left.\hat{f} \xi+C^{\mathrm{l}} m\right)} d \xi . . . . ~ . ~} \tag{3}
\end{equation*}
$$

The proof of Lemma 3.1 can be found in [12].
Lemma 3.2 Let $J$ be a countable indexing set, $\left\{f_{\mathrm{j}}(x) \mid j \in J\right\} \subset L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ and $C \in G L_{\mathrm{n}}(\mathbb{R})$. If ess $\left.\sup _{\xi} \frac{1}{|\operatorname{det} C|}|\hat{\mathrm{j} \in \mathrm{J}}| \overrightarrow{f_{\mathrm{j}}}(\xi)\right|^{2}<\infty$, then for all $f \in \mathcal{D}$, the series in (3) is absolutely convergent.

Proof. Notice that $\left|\overline{f_{\mathrm{j}}}(\xi) \widehat{f_{\mathrm{j}}}\left(\xi+C^{\mathrm{l}} m\right)\right| \leq \frac{1}{2}\left|\widehat{f_{\mathrm{j}}}(\xi)\right|^{2}+\left|\widehat{f_{\mathrm{j}}}\left(\xi+C^{\mathrm{l}} m\right)\right|^{2}$, hence

$$
\begin{aligned}
& { }_{+\frac{1}{2}}^{\mathrm{X} \in \mathrm{~J}} \underset{\mathrm{~m} \neq 0}{\mathrm{X}} \quad \frac{1}{|\operatorname{det} C|}_{\mathbb{R}^{n}}^{\mathrm{Z}}\left|\hat{f}(\xi) \hat{f}\left(\xi+C^{\mathrm{l}} m\right)\right|\left|\hat{j_{\mathrm{j}}}\left(\xi+C^{\mathrm{l}} m\right)\right|^{2} d \xi .
\end{aligned}
$$

Obviously, it is enough to show that the series

$$
\operatorname{lcJ}_{\mathrm{j} \in \mathrm{~J}}^{\mathrm{m} \neq 0} \mathrm{X} \frac{1}{\mid \operatorname{det} C}
$$

Theorem 4.1 Let $J$ be a countable indexing set, $\left\{f_{\mathrm{j}}(x) \mid j \in J\right\} \subset L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ and $C \in G L_{\mathrm{n}}(\mathbb{R})$. Set

If

$$
\begin{equation*}
A_{1}=e s s \inf _{\xi} \frac{1}{|\operatorname{det} C|}_{\mathrm{j} \in \mathrm{~J}}^{\mathrm{X}}\left|\hat{\mathrm{j}}_{\mathrm{j}}(\xi)\right|^{2}-\mathrm{x}>0 \tag{6}
\end{equation*}
$$

and

$$
\begin{equation*}
B_{1}=\left.e s s \sup _{\xi} \frac{1}{|\operatorname{det} C|}_{\mathrm{X} \in \mathrm{~J}}^{\mid \hat{\mathrm{j}}}(\xi)\right|^{2}+\mathfrak{\alpha}<+\infty \tag{7}
\end{equation*}
$$

then $\left\{T_{\mathrm{Ck}} f_{\mathrm{j}}(x) \mid k \in \mathbb{Z}^{\mathrm{n}}, j \in J\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ with bounds $A_{1}$ and $B_{1}$.
Proof. By Lemma 2.1, it is su $\pm$ cient to prove Theorem 4.1 for all $f \in \mathcal{D}$. By (7), Lemma 3.1 and Lemma 3.2, (2)holds, where

$$
\begin{equation*}
R(f)=\mathrm{X}_{\mathrm{m} \neq 0}^{|\operatorname{ldet} C|} \underset{\mathbb{R}^{n}}{\mathrm{f}(\xi) \overline{\hat{f}\left(\xi+C^{\mathrm{l}} m\right)}} \mathrm{X} \overline{\mathrm{j} \in \mathrm{~J}} \overline{\mathrm{f}_{\mathrm{j}}(\xi)} \hat{f_{\mathrm{j}}}\left(\xi+C^{\mathrm{l}} m\right) d \xi \tag{8}
\end{equation*}
$$

By the Cauchy-Schwarz inequality, the change of variables $\eta=\xi+C^{1} m$ and (8), we get

$$
\begin{aligned}
& \tilde{A}_{Z} \\
& {\underset{\mathbb{R}}{ }{ }^{n}}_{\left|\hat{f}\left(\xi+C^{1} m\right)\right|^{2} \mid} \underset{\mathrm{j} \in \mathrm{~J}}{\mathrm{X}} \overline{\hat{f}_{\mathrm{j}}(\xi)} \hat{\hat{f}_{\mathrm{j}}}\left(\xi+C^{1} m\right) \mid d \xi \\
& =\mathbf{X}_{\mathrm{m} \neq 0} \frac{1}{|\operatorname{det} C|} \tilde{\mathbb{A}}_{\mathbf{Z}}\left|\hat{\left.f(\xi)\right|^{2} \mid} \mathrm{X}_{\mathrm{j} \in \mathrm{~J}} \overline{\hat{f_{\mathrm{j}}}(\xi)} \hat{f_{\mathrm{j}}}\left(\xi+C^{\mathrm{l}} m\right)\right| d \xi^{{ }^{\frac{1}{2}}} \times \\
& \tilde{\mathrm{A}}_{Z}\left|\hat{\left.\mathbb{R}^{n}(\eta)\right|^{2} \mid} \mathrm{X} \overline{\hat{f_{j}}(\eta) \hat{f_{j}}}\left(\eta-C^{1} m\right)\right| d \xi^{\frac{1}{2}} \\
& \leq \underbrace{\mathrm{X}}_{m \neq 0}\left(\mathrm{a}_{\mathrm{m}} \mathrm{a}_{-\mathrm{m}}\right)^{\frac{1}{2}}\|f\|^{2} \\
& =\mathfrak{m}\|f\|^{2} .
\end{aligned}
$$

Consequently, by (2), (6), (7) and (9),

$$
A_{1}\|f\|^{2} \leq{\underset{j}{\mathrm{j} \in \mathrm{~J} \mathrm{k} \in \mathbb{Z}^{n}}}_{\mathrm{X}}^{\mathrm{X}}\left|\left\langle f, T_{\mathrm{Ck}} f_{\mathrm{j}}\right\rangle\right|^{2} \leq B_{1}\|f\|^{2}, \quad \forall f \in \mathcal{D}
$$

Therefore, the proof is completed.
Remark 4.1 It is easy to see that frame bounds of above theorem are better than ones of theorem 4.1 in [12].
 then by (8) and the Cauchy-Schwarz inequality, we have

$$
|R(f)| \leq{\underset{\mathrm{m} \neq 0}{\mathrm{X}}}_{\left(\mathfrak{a}_{\mathrm{m}} \mathfrak{a}_{-\mathrm{m}}\right)^{\frac{1}{2}}\|f\|^{2} \leq \mathfrak{a}^{\prime}\|f\|^{2} .}
$$

Now, the second su $\pm$ cient condition is stated.
Theorem 4.2 Let $J$ be a countable indexing set, $\left\{f_{\mathrm{j}}(x) \mid j \in J\right\} \subset L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ and $C \in G L_{\mathrm{n}}(\mathbb{R})$. If

$$
A_{2}=e s s \inf _{\xi} \frac{1}{|\operatorname{det} C|}_{\mathrm{j} \in \mathrm{~J}}^{\mathrm{X}}\left|\hat{f_{\mathrm{j}}}(\xi)\right|^{2}-\mathfrak{x}^{\prime}>0
$$

and

$$
B_{2}=e s s \sup _{\xi} \frac{1}{|\operatorname{det} C|}_{\mathrm{X} \in \mathrm{~J}}^{\left|\hat{f_{\mathrm{j}}}(\xi)\right|^{2}+\mathfrak{x}^{\prime}<+\infty, ~, ~, ~}
$$

then $\left\{T_{\mathrm{Ck}} f_{\mathrm{j}}(x) \mid k \in \mathbb{Z}^{\mathrm{n}}, j \in J\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ with bounds $A_{2}$ and $B_{2}$.
Using another estimation technique, we able to give the third su $\pm$ cient condition for the system $\left\{T_{\mathrm{Ck}} f_{\alpha}(x) \mid k \in \mathbb{Z}^{\mathrm{n}}, \alpha \in \mathfrak{a}\right\}$ to be a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$.

Theorem 4.3 Let $J$ be a countable indexing set, $\left\{f_{\mathrm{j}}(x) \mid j \in J\right\} \subset L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ and $C \in G L_{\mathrm{n}}(\mathbb{R})$. If
and
then $\left\{T_{\mathrm{Ck}} f_{\mathrm{j}}(x) \mid k \in \mathbb{Z}^{\mathrm{n}}, j \in J\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ with bounds $A_{3}$ and $B_{3}$.
Proof. By Lemma 2.1, it is su $\pm$ cient to prove Theorem 4.3 for all $f \in \mathcal{D}$. We need to estimate $R(f)$ in (8). It deduces from the Cauchy-Schwarz inequality and the
change of variables $\eta=\xi+C^{1} m$ that

$$
\begin{aligned}
& \left.\left.\tilde{\mathrm{A}}_{\mathrm{Z}} \underset{\mathbb{R}^{n}}{|\hat{f}(\eta)|^{2}} \underset{\mathrm{~m} \neq 0}{ } \mathrm{X} \frac{1}{|\operatorname{det} C|}\right|_{\mathrm{j} \in \mathrm{~J}} ^{\mathrm{X}} \overline{\hat{f_{\mathrm{j}}}(\eta)} \hat{\mathrm{f}_{\mathrm{j}}}\left(\eta-C^{1} m\right) \right\rvert\, d \xi{ }^{\frac{1}{2}} \\
& \left.=\left.{\underset{\mathbb{R}^{n}}{ }|\hat{f}(\xi)|^{2}}_{\mathrm{X} \neq 0}^{\mathrm{X}} \frac{1}{|\operatorname{det} C|}\right|_{\mathrm{j} \in \mathrm{~J}} ^{\mathrm{X}} \overline{\hat{\hat{j}^{\prime}}(\xi)} \hat{\hat{\mathrm{j}}_{\mathrm{j}}}\left(\xi+C^{\mathrm{l}} m\right) \right\rvert\, d \xi .
\end{aligned}
$$

By (2), (10), (11) and (12), we have

Therefore, the proof of Theorem 4.3 is completed.
Remark 4.3 Obviously, frame bounds of this theorem are better than ones of theorem 4.2, and are also better than theorem 4.2 in [12].
5. Applications of main results to Gabor system

In this section, we apply Theorems 4.1, 4.2 and 4.3 to Gabor system, and then obtain some new results of Gabor frames. Let $g^{\prime}(x) \in L^{2}\left(\mathbb{R}^{\mathrm{n}}\right), l=1, \cdots, L, L$ be a positive integer and $g_{\mathrm{m}, \mathrm{k}}^{\prime}=M_{\mathrm{Bm}} T_{\mathrm{Ck}} g^{\prime}$. The Gabor system, which generated by $g^{\prime}(x)(l=1, \cdots, L)$, is de ned by

$$
\left\{g_{\mathrm{m}, \mathrm{k}}^{\prime}(x) \mid m, k \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}
$$

where $B, C \in G L_{\mathrm{n}}(\mathbb{R})$. If we change the order of the translation and modulation operators, we also have the system

$$
\left\{T_{\mathrm{Ck}} M_{\mathrm{Bm}} g^{\prime}(x) \mid m, k \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\} .
$$

It is immediate to see that $\left\{g_{\mathrm{m}, \mathrm{k}}^{\mathrm{l}}(x) \mid m, k \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ if and only if $\left\{T_{\mathrm{Ck}} M_{\mathrm{Bm}} g^{\prime}(x) \mid m, k \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$, and
the frame bounds is the same in the two cases. In particular, $\left\{T_{\mathrm{Ck}} M_{\mathrm{Bm}} g^{\prime}(x) \mid m, k \in\right.$ $\left.\mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$ is shift-invariant. So, the main results can apply directly to the Gabor system.

Let $J$ be de ned by $J=\left\{(l, m) \mid m \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$, and $\forall \gamma \in J, f_{\mathrm{Y}}(x)=$ $M_{\mathrm{B} m} g^{\prime}(x)$. Then thesystem $\left\{T_{\mathrm{Ck}} f_{\mathrm{Y}}(x) \mid k \in \mathbb{Z}^{\mathrm{n}}, \gamma \in J\right\}$ is thesystem $\left\{T_{\mathrm{Ck}} M_{\mathrm{B} m} g^{\prime}(x) \mid m, k \in\right.$ $\left.\mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$. Notice that $\forall \gamma=(l, m) \in J, \hat{\hat{y}_{\mathrm{y}}}(\xi)=\hat{g}^{\prime}(\xi-B m)$, hence $\forall k \in \mathbb{Z}^{\mathrm{n}}$,

Therefore, using Theorem 4.1, Theorem 4.2 and Theorem 4.3, respectively, we obtain
Theorem 5.1 Let $B, C \in G L_{\mathrm{n}}(\mathbb{R}), g^{\prime}(x) \in L^{2}\left(\mathbb{R}^{\mathrm{n}}\right), l=1, \cdots, L$ and $L$ be $a$ positive integer. If

$$
\begin{aligned}
& C_{1}=e s s \inf _{\xi} \frac{1}{|\operatorname{det} C|} \quad \begin{array}{l}
\mathrm{I}=1 \\
\mathrm{~m} \in \mathbb{Z}^{n}
\end{array}\left|\hat{g}^{\wedge}(\xi-B m)\right|^{2}-\Theta_{\mathrm{G}}>0,
\end{aligned}
$$

then $\left\{g_{\mathrm{m}, \mathrm{k}}^{1}(x) \mid m, k \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ with bounds $C_{1}$ and $D_{1}$, where


Theorem 5.2 Let $B, C \in G L_{\mathrm{n}}(\mathbb{R}), g^{\prime}(x) \in L^{2}\left(\mathbb{R}^{\mathrm{n}}\right), l=1, \cdots, L$ and $L$ be $a$ positive integer. If

$$
\begin{aligned}
& C_{2}=e s s \inf _{\xi} \frac{1}{|\operatorname{det} C|} \times \underset{\mathrm{I}=1}{\mathrm{~m} \in \mathbb{Z}^{n}}\left|\hat{g}^{\prime}(\xi-B m)\right|^{2}-\Theta_{\mathrm{G}}^{\prime}>0, \\
& D_{2}=e s s \sup _{\xi} \frac{1}{|\operatorname{det} C|} \quad \times \quad \times \underset{\mathrm{I}=1}{\mathrm{~m} \in \mathbb{Z}^{n}}\left|\hat{g}^{\prime}(\xi-B m)\right|^{2}+\Theta_{\mathrm{G}}^{\prime}<\infty,
\end{aligned}
$$

then $\left\{g_{\mathrm{m}, \mathrm{k}}^{1}(x) \mid m, k \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ with bounds $C_{2}$ and $D_{2}$, where

Remark 5.1 In one dimensional case, theorem 5.2 was given in [13].
Theorem 6.3 Let $B, C \in G L_{\mathrm{n}}(\mathbb{R}), g^{\prime}(x) \in L^{2}\left(\mathbb{R}^{\mathrm{n}}\right), l=1, \cdots, L$ and $L$ be $a$ positive integer. If
then $\left\{g_{\mathrm{m}, \mathrm{k}}^{1}(x) \mid m, k \in \mathbb{Z}^{\mathrm{n}}, l=1, \cdots, L\right\}$ is a frame for $L^{2}\left(\mathbb{R}^{\mathrm{n}}\right)$ with bounds $C_{3}$ and $D_{3}$.

Remark 5.2 If $n=1$ and $L=1$, then theorem 5.3 is just theorem 8.4.4 in [9]. In addition, the upper bound of theorem 5.3 is superior to one of theorem 2.3 in [13].

Since $\left\langle f, T_{\mathrm{Ck}} M_{\mathrm{B} m} g^{\prime}\right\rangle=\left\langle f^{\vee},\left(T_{\mathrm{Ck}} M_{\mathrm{B}} g^{\prime}\right)^{\vee}\right\rangle=\left\langle f^{\vee}, T_{-\mathrm{Bm}} M_{\mathrm{Ck}}\left(g^{\mathrm{I}}\right)^{\vee}\right\rangle$ by thePlanchere Theorem, we able to present similar results in the time domain. Them were omitted here

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